CN8033

H-Bridge Motor Driver 4~24V, 0.6Ω Peak current limiting protection:3.5A

1 Description

The CN8033 is a H-bridge motor driver used for driving reversible motors, which can drive one DC motor, a stepper motor, or other loads.

The CN8033 operates on a motor power supply voltage from 4V to 24V, With 3.5A current limit.

The CN8033 is controlled by two input pins. The two logic level inputs determine the output mode: forward, reverse, coast, or brake. Very low standby circuit current can be achieved when the two inputs are both at a low level.

The CN8033 is available with SOT23-6, SOP-8 and ESOP-8 package.

2 Features

- Wide Power Range: 4V to 24V
- Peak current limiting protection:3.5A
- Low MOSFET On Resistance: Rhs=0.4Ω, Rls=0.2Ω
- Forward, Reverse, Coast, or Brake Output Modes
- Suitable for wide range MCU control logic
- Input logic hysteresis
- Thermal Shutdown

3 Applications

- Smart Circuit Breaker
- Smart Locks
- Smart Water/Gas Meter
- Toys

4 Ordering information

Product Number	Package	Quantity/Tape
CN8033TSR	SOT23-6	3000/Reel
CN8033SHR	SOP-8	2500/Reel 4000/Reel
CN8033EHR	ESOP-8	2500/Reel 4000/Reel
CN8033BSHR	SOP-8	2500/Reel 4000/Reel
CN8033CSHR	SOP-8	4000/Reel
CN8033DSHR	SOP-8	4000/Reel

5 Marking

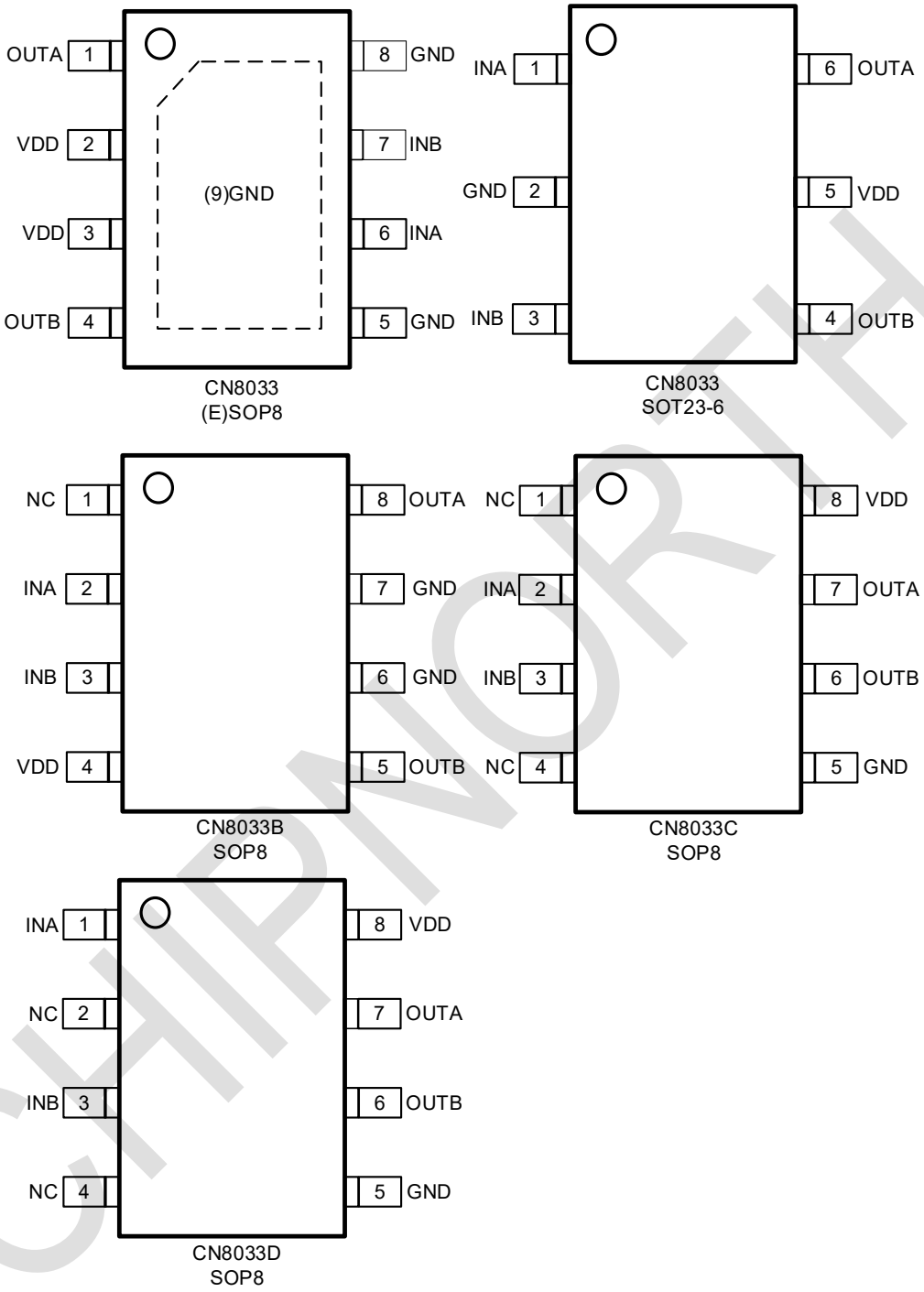
Product Number	Marking
CN8033TSR	CN8033T YYWW
CN8033SHR	CN8033 KYYWW
CN8033EHR	CN8033 KYYWW
CN8033BSHR	CN8033B KYYWW
CN8033CSHR	CN8033C YYWW
CN8033DSHR	CN8033D YYWW

Note: YY=Year WW=Week.

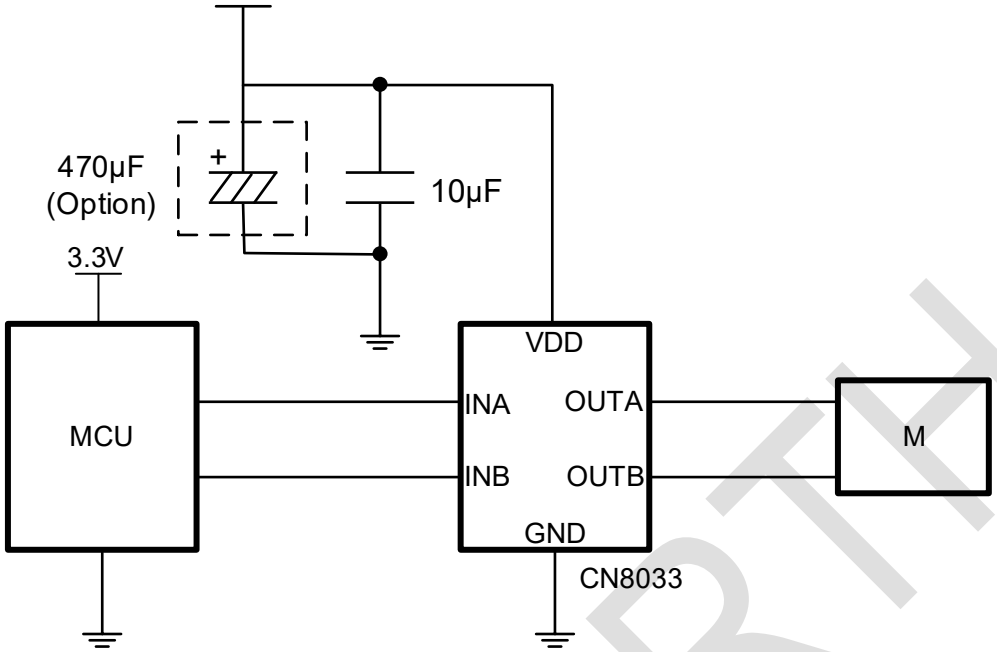
Green (RoHS & HF): CHIPNORTH defines "Green" to mean Pb-Free (RoHS compatible) and free of halogen substances. If you have additional comments or questions, please contact your CHIPNORTH representative directly.

Moisture sensitivity level(MSL):3

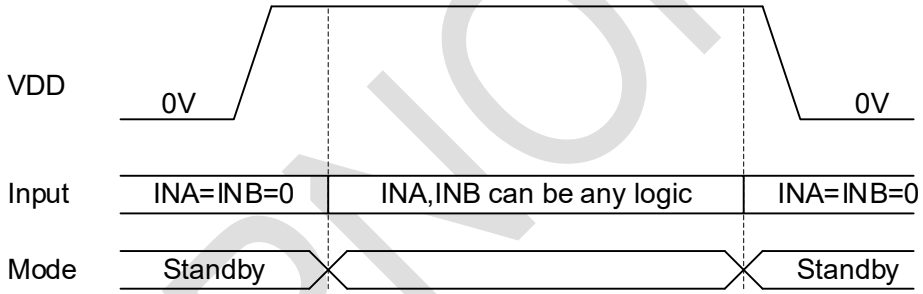
6 Pinout



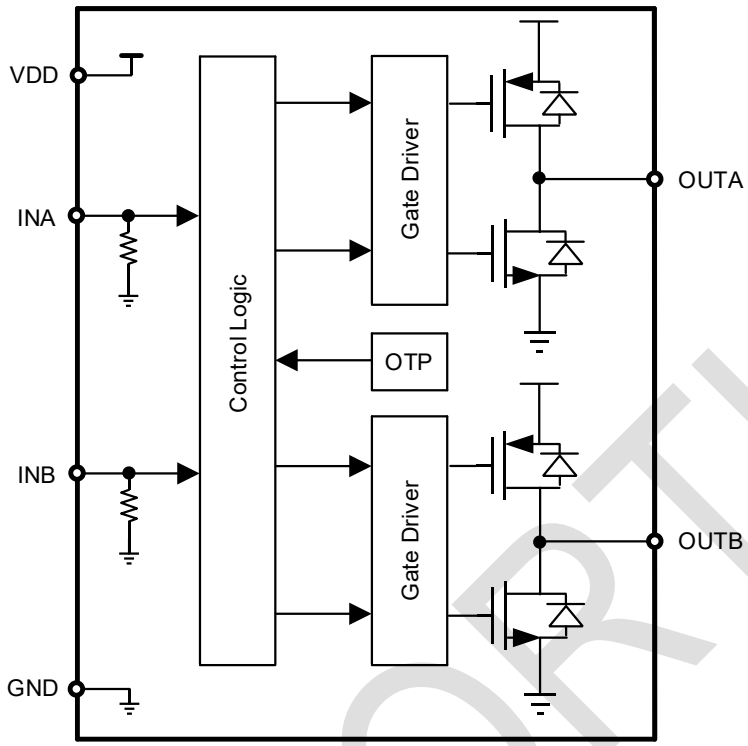
7 Typical Application



Please make sure that the input pins INA and INB remain low during power-up and power-down.



8 Block Diagram



9 Logic Function Table

INA	INB	OUTA	OUTB
0	0	Hi-Z	Hi-Z
0	1	0	1
1	0	1	0
1	1	0	0

10 Pin Descriptions

PIN							Description
CN8033 TSR	CN8033 SHR	CN8033 EHR	CN8033B SHR	CN8033C SHR	CN8033D SHR	Name	
6	1	1	8	7	7	OUTA	Output, connect this pin to the motor winding.
5	2/3	2/3	4	8	8	VDD	Supply Voltage. A capacitor is required to prevent large voltage spikes.
4	4	4	5	6	6	OUTB	Output, connect this pin to the motor winding.
2	5/8	5/8	6/7	5	5	GND	GND.
1	6	6	2	2	1	INA	Logic input with a 1.2MΩ pull-down resistor.
3	7	7	3	3	3	INB	Logic input with a 1.2MΩ pull-down resistor.
/	/	9	/	/	/	EPad	Recommended to be connected to GND.
/	/	/	1	1/4	2/4	NC	Recommended to be connected to GND.

11 Specifications

11.1 Absolute Maximum Ratings

Parameter	Symbol	Value	Units
VDD Supply Voltage Range	V_{DD}	-0.4 ~ +25	V
INA/INB Supply Voltage Range	V_{INX}	-0.4 ~ +7	V
OUTA/OUTB Supply Voltage Range	V_{OUTX}	-0.4 ~ +25	V
Storage Temperature Range	T_{STG}	-55~150	°C
Welding Temperature	T_{LEAD}	260（soldering,10s）	°C

Note：

1.Stress exceeds these ratings listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Expose to absolute-maximum-rated conditions for extended periods may affect device reliability.

2.All voltage values are referenced to the ground terminal.

11.2 ESD Ratings

Discharge mode	Value	Units
HBM	±3500	V
CDM	±2000	V

11.3 Recommended Operating Range

Parameter	Symbol	Min.	Max.	Units
Input Voltage	V_{DD}	4	24	V
Input Logic Level	V_{INx}	0	7	V
Operating Ambient Temperature Range	T_A^*	-40	105	°C

*Note: Calculate the maximum ambient temperature based on the specific thermal resistance.

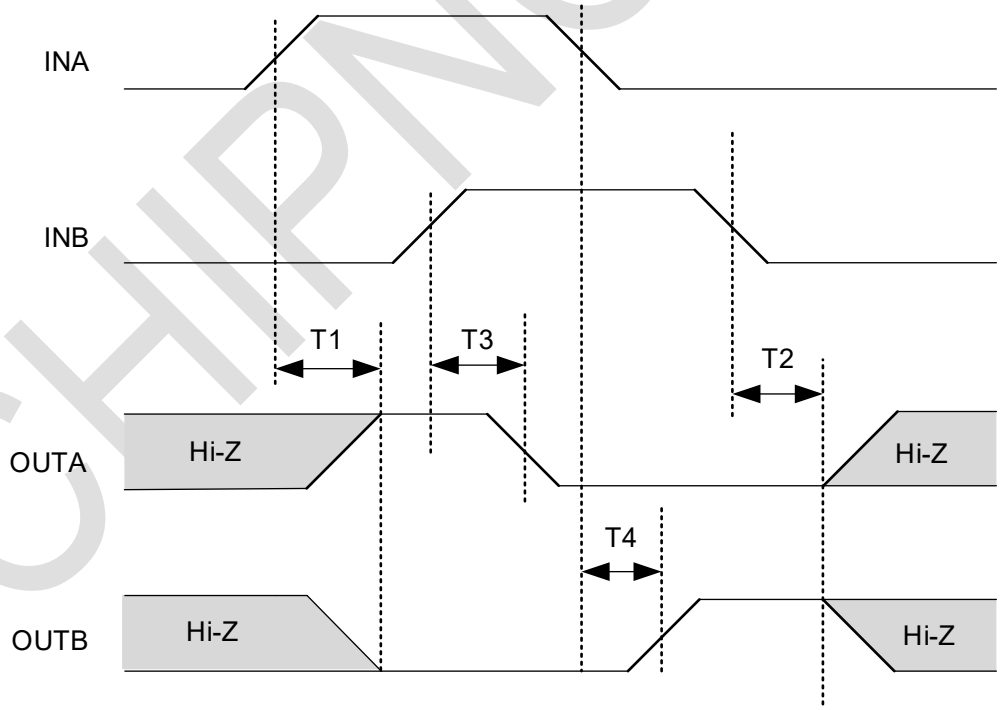
11.4 Thermal Information

Parameter	Package	Value	Unit
θJA	SOT23-6	180	°C/W
	SOP-8	100	°C/W
	ESOP-8	60	°C/W

11.5 Electrical Characteristics

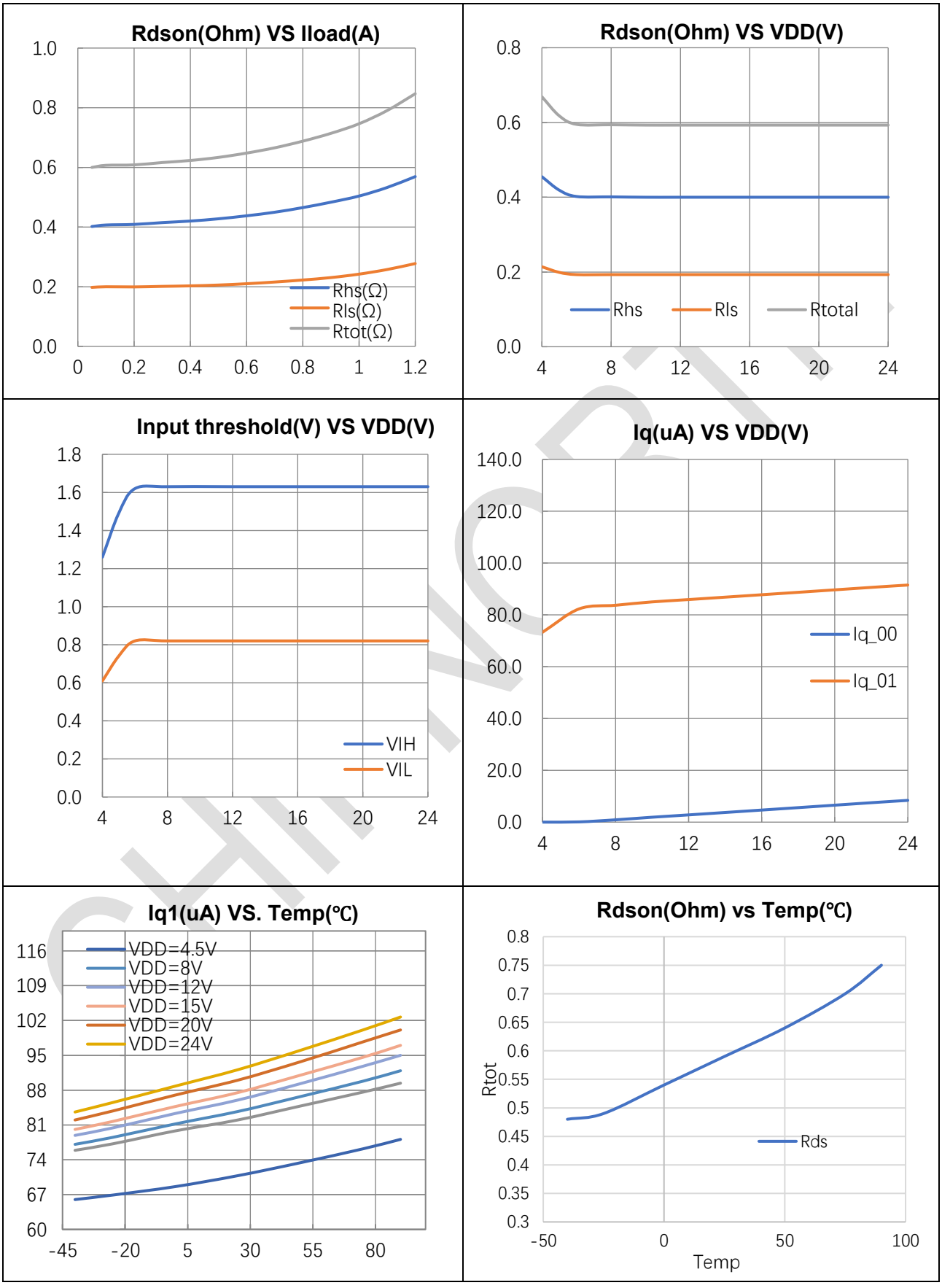
Test conditions: T_A = 25°C, VDD=12V, unless otherwise noted.

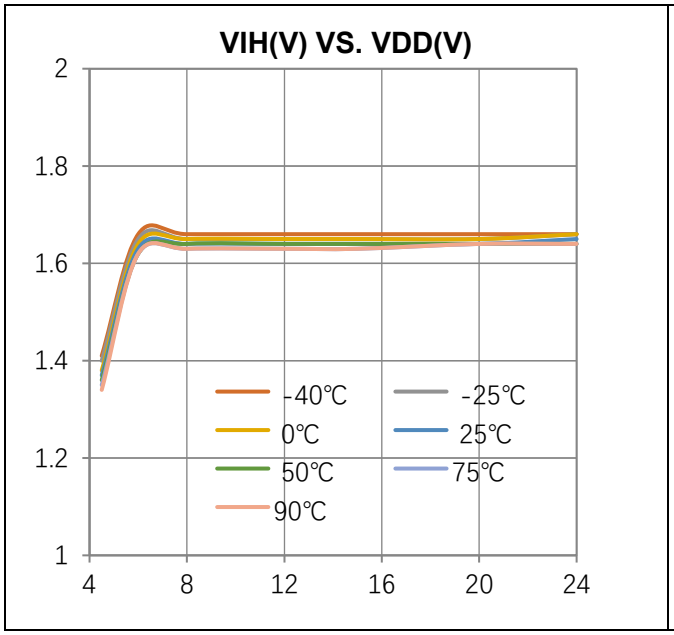
Parameters	Symbol	Condition	Min	Typ.	Max	Units
Operating supply voltage	VDD		4		24	V
Standby mode supply current	Iq0	INA=INB=0V		3		μA
Operating supply current	Iq1			85		μA
UVLO threshold rising				4.0	4.4	V
UVLO hysteresis				0.15		V
Input high voltage	VIH		1.7			V
Input low voltage	VIL				0.8	V
INx Input current	I_INx	V_INx=3.3V		2.4		μA
Input pull-down resistance	RIN			1.2		MΩ
HS switch on resistance	Rhs	ILOAD=300mA	0.4	0.45	0.6	Ω
LS switch on resistance	Rls	ILOAD=300mA	0.2	0.25	0.4	Ω
Output enable time	T1			1000		ns
Delay time	T3	INB high to OUTA low		200		ns
	T4	INA low to OUTB high		300		ns
Dead time				200		ns
Thermal shutdown threshold				155		°C
Thermal shutdown hysteresis				25		°C
Current limit				3.5		A

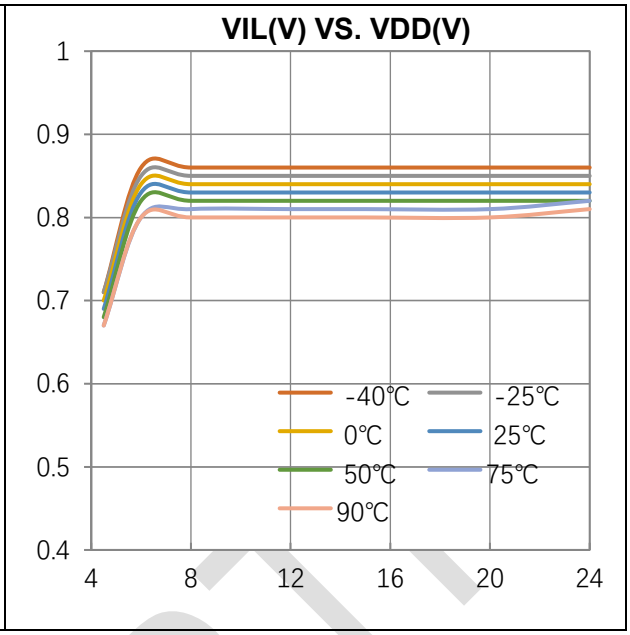


11.6 Characteristics Curve

Test conditions: VDD=12V, TA=25°C, unless otherwise noted.




VIH(V) VS. VDD(V)
2
1.8
1.6
1.4
1.2
1
4
8
12
16
20
24
-40℃
-25℃
0℃
25℃
50℃
75℃
90℃


VIL(V) VS. VDD(V)
1
0.9
0.8
0.7
0.6
0.5
0.4
4
8
12
16
20
24
-40℃
-25℃
0℃
25℃
50℃
75℃
90℃

12 Detailed Description

12.1 Overview

The CN8033 is an H-bridge driver that can drive a DC motor or other devices such as solenoid valves. Outputs can be controlled via the CN8033's PWM interfaces (INA and INB). These devices integrate the necessary driver FETs and FET control circuits, thereby greatly reducing the number of components in a motor driver system. In addition, the CN8033 adds protection functions that go beyond conventional discrete implementations: overcurrent protection and thermal shutdown.

12.2 Rotation Speed Adjustment

PWM (Pulse Width Modulation) technology achieves precise control of motor speed by adjusting the duty cycle of the pulse signal. This technique regulates the average value of the motor input voltage and thus controls the motor speed by changing the duty cycle of the PWM signal, i.e., the ratio of the pulse width to the pulse period. Specifically, the larger the duty cycle of the PWM signal, the higher the average value of the motor input voltage and the faster the motor speed; on the contrary, the smaller the duty cycle, the slower the motor speed.

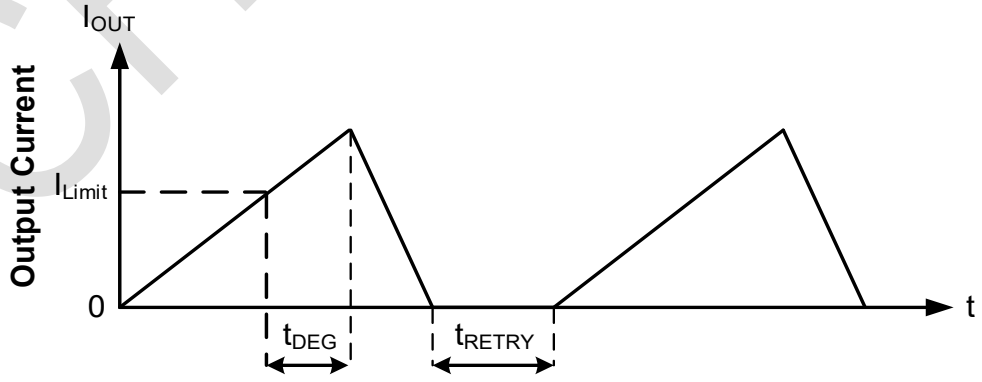
12.3 Motor Controls

The CN8033 is controlled via PWM input connectors (INA and INB connectors). Each output is controlled by the corresponding input pin.

INA	INB	OUTA	OUTB	Functions (DC motors)
L	L	Hi-Z	Hi-Z	Coast
L	H	L	H	Reverse
H	L	H	L	Forward
H	H	L	L	Brake

12.4 Over Current Protection

There is an analog current limit circuit on each field effect transistor that limits the current through the field effect transistor by eliminating gate drive. If the analog current limit analog current limit lasts longer than t_{DEG}, all field effect transistors in the H-bridge are disabled. Operation is automatically resumed after t_{RETRY}. Overcurrent of the field effect transistors is detected by both the high voltage side and the low voltage side FETs. overcurrent can be caused by a short circuit between the OUTA pin and the OUTB pin or by grounding the OUTB pin.

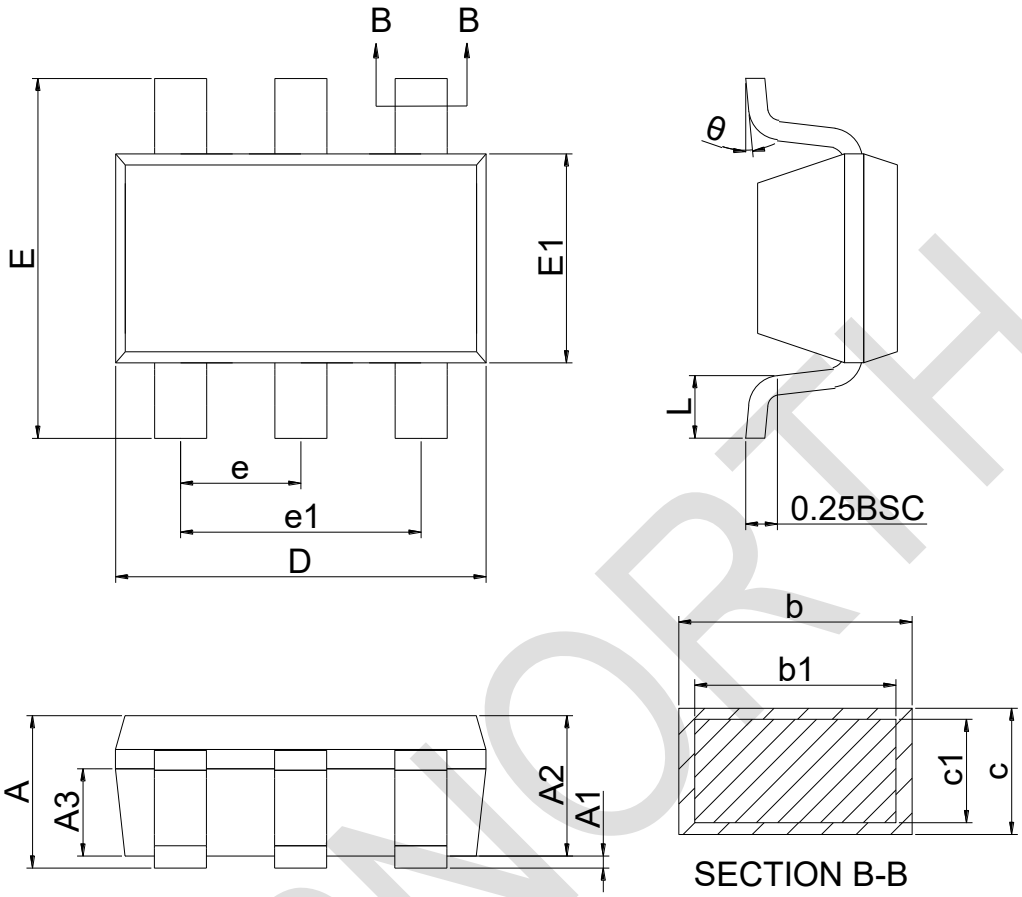


12.5 Over Temperature Protection

If the chip temperature exceeds 155°C, all field effect tubes in the H-bridge are disabled. Operation is automatically resumed when the chip temperature drops below 130°C.

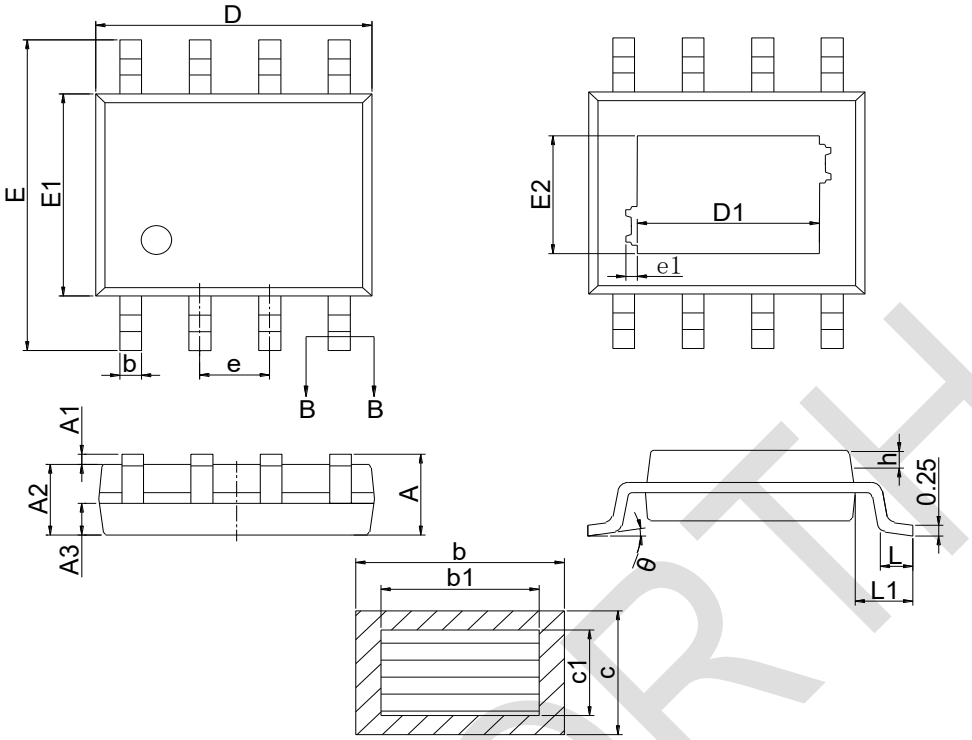
13 Package Information

SOT23-6



Dimension / Symbol	Min (mm)	Nom (mm)	Max (mm)
A			1.25
A1	0.04		0.10
A2	1.00	1.10	1.20
A3	0.55	0.65	0.75
b	0.38		0.48
b1	0.37	0.40	0.43
c	0.11		0.21
c1	0.10	0.13	0.16
D	2.72	2.92	3.12
E	2.60	2.80	3.00
E1	1.40	1.60	1.80
e	0.95BSC		
e1	1.90BSC		
L	0.30		0.60
θ	0°		8°

ESOP-8



SECTION B-B

Dimension / Symbol	Min (mm)	Nom (mm)	Max (mm)
A			1.65
A1	0.05		0.15
A2	1.30	1.40	1.50
A3	0.60	0.65	0.70
b	0.39		0.47
b1	0.38	0.41	0.44
c	0.20		0.24
c1	0.19	0.20	0.21
D	4.80	4.90	5.00
E	5.80	6.00	6.20
E1	3.80	3.90	4.00
e	1.05REF		
h	0.25		0.50
L	0.50	0.60	0.80
L1	1.05REF		
θ	0°		8°

Size(mm) / L/F Size(nil)	D1	E2	e1
95*130	3.10REF	2.21REF	0.10REF

Note：SOP-8 has no heat dissipation pad, other dimensions are the same as ESOP-8

14 Important Statement

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